## Up-Dating a Linear-Stiffness Model with Uncertain Non-Linearity Yakov Ben-Haim Technion—Israel Institute of Technology yakov@technion.ac.il, info-gap.com

**The problem.** We will use measurements to estimate the stiffness, k, of a 1-dimensional spring, where force f is assumed to be related to displacement x by a linear model: f = kx. However, we suspect that the spring may actually have a cubic non-linearity:  $f = kx + k_3x^3$ . The non-linear stiffness  $k_3$  is highly uncertain, and for practical reasons we do not include this non-linearity in the up-dated model. We will describe an info-gap robust-satisficing approaching to up-dating the linear model given measurements, and subject to the uncertain non-linearity. More advanced analysis is available in the references cited below.

Mean squared estimates. Our force-deflection measurements are  $(x_i, f_i)$ , i = 1, ..., n. For any choice of the linear stiffness, k, the mean squared error (MSE) of the linear model is:

$$S = \frac{1}{n} \sum_{i=1}^{n} (f_i - kx_i)^2 \tag{1}$$

The value of k which minimizes this MSE is denoted  $\hat{k}$ .

The actual MSE, accounting for the uncertain non-linearity, is:

$$S(k,k_3) = \frac{1}{n} \sum_{i=1}^{n} (f_i - kx_i - k_3 x_i^3)^2$$
(2)

**Robustness.** We wish to choose the linear stiffness, k, so that the actual MSE is adequately small and so that we are robust to the uncertain non-linearity.

Consider a uniform-bound info-gap model for uncertainty in the cubic term:

$$\mathcal{U}(h) = \{k_3 : |k_3| \le h\}, \quad h \ge 0$$
(3)

This is an unbounded family of nested sets of  $k_3$  values. There is no probabilistic information and no known worst case.

The robustness of the linear model with coefficient k is the greatest horizon of uncertainty, h, up to which the actual mean squared error does not exceed  $S_c$ :

$$\widehat{h}(k, S_{c}) = \max\left\{h: \left(\max_{k_{3} \in \mathcal{U}(h)} S(k, k_{3})\right) \le S_{c}\right\}$$
(4)



Figure 1: Robustness curves.  $\hat{k} = 1.8681$  (solid, least squares value), k = 1.75 (- -), k = 1.81 (-.). Data:  $x^T = (1, 2, 3, 4, 5, 6), f^T = (2.0, 3.6, 6.6, 7.8, 9.6, 10.3).$ 

<sup>&</sup>lt;sup>0</sup>\website\igt\simple-examples\model-update-uncer-nonlin01.tex 26.3.2009 ©Yakov Ben-Haim.

Fig. 1 shows robustness curves for three different choices of the linear stiffness coefficient. The MSE optimal coefficient is  $\hat{k} = 1.8681$ , whose robustness curve (solid line) sprouts from the  $S_c$ -axis to the left of all other curves. However, the robustness is zero for  $S_c$  values on the horizontal axis. Furthermore, the robustness curve for k = 1.81 crosses the MSE optimal curve at low robustness. This implies that k = 1.81 is a more reliable choice for the stiffness of the linear model in light of the uncertain non-linearity. The robustness curve for k = 1.75 lies below the other curves and thus k = 1.75 would never be chosen.

## Sources.

• Yakov Ben-Haim, 2009, Up-Dating a Linear System with Model Uncertainty: An Info-Gap Approach, working paper.

• Yakov Ben-Haim and Scott Cogan, 2009, Linear Bounds on an Uncertain Non-Linear Oscillator: An Info-Gap Approach, working paper.