

Lecture 3
Probabilistic Reliability
with
Info-Gap Uncertainty

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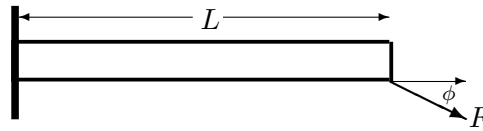
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1 Highlights

§ Info-Gap Robustness Analysis of:

- Random Loads on a Beam.
- Random Events and Failure.

2 Random Load on a Cantilever: Info-Gap Robustness Analysis



2.1 Problem Statement

- Rigid beam.
- F = load at free end at angle ϕ .
- k = rotational stiffness at base.
- θ = angular rotation of beam:

$$\theta = \frac{F \sin \phi}{k} \quad (1)$$

- Design requirement:

$$|\theta| \leq \theta_c \quad (2)$$

- Problem: Load uncertain, F .

2.2 Uniform-Bound Info-Gap Model

§ We know:

- F is nominally zero.
- F may deviate greatly from zero.

§ We do not know:

- Maximum deviation from zero.
- Probability distribution of F .

§ Info-gap model of uncertainty in F :

$$\mathcal{U}(h) = \{F : |F| \leq h\}, \quad h \geq 0 \quad (3)$$

Two levels of uncertainty:

- F unknown.
- Horizon of uncertainty, h , unknown.

§ Derive the robustness by combining:

- System model: eq.(1).
- Performance requirement: eq.(2).
- Uncertainty model: eq.(3).

$$\hat{h}(\theta_c) = \max \left\{ h : \left(\max_{F \in \mathcal{U}(h)} |\theta| \right) \leq \theta_c \right\} \quad (4)$$

§ **Solution method.** Start from the inside:

Let $m(h)$ denote the inner maximum in eq.(4) that occurs for $F = \pm h$:

$$m(h) = \left| \frac{h \sin \phi}{k} \right| \leq \theta_c \implies \boxed{\hat{h}(\theta_c) = \frac{k\theta_c}{\sin \phi}} \quad (5)$$

§ **Two properties** of all info-gap robustness functions, $\hat{h}(\theta_c)$:

- **Trade off:** Better performance (smaller θ_c) has worse robustness (lower \hat{h}).
- **Zeroing:** Predicted performance (no rotation) has zero robustness.

§ **Inverse of robustness:** $m(h)$ is the inverse function of $\hat{h}(\theta_c)$:

$$m(h) = \theta_c \text{ if and only if } \hat{h}(\theta_c) = h \quad (6)$$

Hence: plot of $m(h)$ vs h is the same as plot of θ_c vs $\hat{h}(\theta_c)$.

2.3 Fractional-Error Info-Gap Model

§ **Different information, different robustness.**

§ **We know:**

- F nominally equals \tilde{F} , a known positive value.
- F may deviate greatly from \tilde{F} .
- k nominally equals \tilde{k} , a known positive value.
- k may deviate greatly from \tilde{k} .
- k is non-negative.

§ **We do not know:**

- Maximum fractional deviation of F from \tilde{F} , or of k from \tilde{k} .
- Probability distribution of F or of k .

§ **Info-gap model** of uncertainty in F and k :

$$\mathcal{U}(h) = \left\{ F, k : \left| \frac{F - \tilde{F}}{\tilde{F}} \right| \leq h, k > 0, \left| \frac{k - \tilde{k}}{\tilde{k}} \right| \leq h \right\}, \quad h \geq 0 \quad (7)$$

§ **Derive the robustness** by combining:

- System model: eq.(1), p.4: $\theta = (F \sin \phi)/k$.
- Performance requirement: eq.(2), p.4: $|\theta| \leq \theta_c$.
- Uncertainty model: eq.(7).

$$\hat{h}(\theta_c) = \max \left\{ h : \left(\max_{F, k \in \mathcal{U}(h)} |\theta| \right) \leq \theta_c \right\} \quad (8)$$

§ **Solution method:** start with the inner maximum of eq.(8).

The inner maximum, $m(h)$, occurs at:

$$F = (1 + h)\tilde{F}, \quad k = \max[0, (1 - h)\tilde{k}] \quad (9)$$

Thus, for $h < 1$:

$$m(h) = \frac{(1+h)\tilde{F} \sin \phi}{(1-h)\tilde{k}} \leq \theta_c \implies (1+h)\tilde{F} \sin \phi \leq (1-h)\tilde{k}\theta_c \implies \hat{h} = \frac{\tilde{k}\theta_c - \tilde{F} \sin \phi}{\tilde{k}\theta_c + \tilde{F} \sin \phi} \quad (10)$$

or zero if this is negative. Note that \hat{h} is less than 1.

§ **Two properties:**

- Trade off: greater robustness only at greater allowed deflection.
- Zero robustness at estimated deflection.

§ **Meaning of numerical values of \hat{h} :**

- $\hat{h} = 0.2$ implies performance guaranteed up to 20% error in both \tilde{F} and \tilde{k} .
- $\hat{h} = 0.7$ implies performance guaranteed up to 70% error in both \tilde{F} and \tilde{k} .
- Asymptotic robustness:

$$\lim_{\theta_c \rightarrow \infty} \hat{h}(\theta_c) = 1 \quad (11)$$

- Max possible robustness (in this problem:) immunity to 100% error.
 - Small? Large? Large enough?
 - Important and difficult **value judgment**.

2.4 Probability of Failure

§ Different prior knowledge:

- k is known.
- F is exponentially distributed random variable:

$$p(F) = \lambda e^{-\lambda F}, \quad F \geq 0 \quad (12)$$

§ **Failure of failure:**

- **Mechanical** failure [violating design requirement, eq.(2)]:

$$|\theta| > \theta_c \quad (13)$$

- **Probability** of failure:

$$P_f = \text{Prob}(|\theta| > \theta_c) \quad (14)$$

§ **Deriving probability of failure:**

F is non-negative so θ is also non-negative. Hence the probability of failure is:

$$P_f(\lambda) = \text{Prob}(|\theta| > \theta_c) = \text{Prob}(\theta > \theta_c) = \text{Prob}\left(\frac{F \sin \phi}{k} > \theta_c\right) = \text{Prob}\left(F > \frac{k\theta_c}{\sin \phi}\right) = \exp\left(-\frac{\lambda k\theta_c}{\sin \phi}\right) \quad (15)$$

2.5 Hybrid Uncertainty: Probability with Info-Gaps

§ Continue from section 2.4, but with λ **uncertain**.

§ **We know:**

- $\tilde{\lambda}$, an estimate of λ .
- λ is positive.

§ **We do not know:**

- Maximum fractional error of the estimate.
- Probability distribution of λ .

§ **Info-gap model** for uncertainty in λ :

$$\mathcal{U}(h) = \left\{ \lambda : \lambda > 0, \left| \frac{\lambda - \tilde{\lambda}}{\tilde{\lambda}} \right| \leq h \right\}, \quad h \geq 0 \quad (16)$$

§ **Two types of failure:**

- **Mechanical failure.** Rotation too large:

$$|\theta| > \theta_c \quad (17)$$

- **Probabilistic failure.** Probability of failure too large:

$$\text{Prob}(|\theta| > \theta_c) > P_c \quad (18)$$

§ **Evaluate robustness** with respect to probabilistic failure:

$$\hat{h} = \max \left\{ h : \left(\max_{\lambda \in \mathcal{U}(h)} P_f(\lambda) \right) \leq P_c \right\} \quad (19)$$

- Start with the inner maximum of eq.(19), $m(h)$.
- From eq.(15), p.6, the inner maximum occurs at $\lambda = \max[0, (1-h)\tilde{\lambda}]$:

$$m(h) = \exp \left(-\frac{(1-h)\tilde{\lambda}k\theta_c}{\sin \phi} \right) \leq P_c \implies \frac{(1-h)\tilde{\lambda}k\theta_c}{\sin \phi} \geq -\ln P_c \implies \boxed{\hat{h}(P_c) = 1 + \frac{\sin \phi}{\tilde{\lambda}k\theta_c} \ln P_c} \quad (20)$$

or zero if this is negative.

§ **Two properties:**

- **Trade off:** $\hat{h}(P_c)$ decreases (gets worse) as P_c decreases (gets better).
- **Zeroing:** Robustness vanishes at nominal P_f :

$$\hat{h}(P_c) = 0 \quad \text{if} \quad P_c = P_f(\tilde{\lambda}) = \exp \left(-\frac{\tilde{\lambda}k\theta_c}{\sin \phi} \right) \quad (21)$$

3 Random Events and Failure: Info-Gap Robustness Analysis

3.1 Formulation

§ Problem Statement:

- **Adverse events occur** randomly, independently, with average rate λ /sec.
- **System fails** if n or more events occur within time T .

§ Questions:

- What is probability of failure if $n = 1$ or $n = 2$?
- Suppose λ is uncertain. Evaluate robustness of failure probability.

3.2 Probabilities of Failure

§ Adverse events occur according to a **Poisson process**:

- Independent random events, constant average rate.
- Probability of exactly n events in duration T is:

$$P_n(T) = \frac{(\lambda T)^n}{n!} e^{-\lambda T}, \quad n = 0, 1, 2, \dots \quad (22)$$

§ Failure probability for $n = 1$:

- The probability of **no** events up to time T is $P_0(T)$.
- Thus, for $n = 1$, the probability of failure is $1 - P_0(T)$:

$$P_{f,1} = 1 - e^{-\lambda T} \quad (23)$$

§ Failure probability for $n = 2$:

- The probability of less than 2 events up to time T is $P_0(T) + P_1(T)$.
- Thus, for $n = 2$, the probability of failure is $1 - P_0(T) - P_1(T)$:

$$P_{f,2} = 1 - e^{-\lambda T} - \lambda T e^{-\lambda T} \quad (24)$$

3.3 Uncertain Poisson Process

§ **We know:**

- $\tilde{\lambda}$ = estimate of failure rate, λ .
- s = estimate of error of $\tilde{\lambda}$.
- λ is positive.

§ **We do not know:**

- True value of λ .
- Maximum fractional error of estimate.
- Probability distribution for λ .

§ **Info-gap model** for uncertainty in λ :

$$\mathcal{U}(h) = \left\{ \lambda : \lambda > 0, \left| \frac{\lambda - \tilde{\lambda}}{s} \right| \leq h \right\}, \quad h \geq 0 \quad (25)$$

§ **Two properties of all info-gap models:**

- **Contraction:**

$$\mathcal{U}(h) = \{ \tilde{\lambda} \} \quad (26)$$

- **Nesting:**

$$h < h' \implies \mathcal{U}(h) \subseteq \mathcal{U}(h') \quad (27)$$

3.4 Robustness to Info-Gap Uncertainty in Poisson Process

§ **System model:** $P_{f,n}$ in eq.(23) or (24).

§ **Performance requirement.** Failure probability acceptably small:

$$P_{f,n} \leq P_c \quad (28)$$

§ **Uncertainty model:** eq.(25).

§ **Robustness function combines** system model, performance requirement, and uncertainty model.

§ **Evaluating the robustness** for $n = 1$.

- The robustness is defined as:

$$\hat{h}_1(P_c) = \max \left\{ h : \left(\max_{\lambda \in \mathcal{U}(h)} P_{f,1} \right) \leq P_c \right\} \quad (29)$$

- Let $m_1(h)$ denote the inner maximum of eq.(29).
- According to eq.(23), $m(h)$ occurs when λ is as large as possible: $\lambda = \tilde{\lambda} + sh$. Thus:

$$m_1(h) = 1 - e^{-(\tilde{\lambda}+sh)T} \leq P_c \implies \hat{h}_1(P_c) = \frac{-\tilde{\lambda}T - \ln(1 - P_c)}{sT} \quad (30)$$

or zero if this is negative.

- Note trade off and zeroing.

§ **Evaluating the inverse of the robustness** for $n = 2$.

- The robustness is defined as:

$$\hat{h}_2 = \max \left\{ h : \left(\max_{\lambda \in \mathcal{U}(h)} P_{f,2} \right) \leq P_c \right\} \quad (31)$$

- Let $m_2(h)$ denote the inner maximum of eq.(31), which is the **inverse of the robustness**.
- From eq.(24), p.8, we find:

$$\frac{\partial P_{f,2}}{\partial \lambda} = \lambda T^2 e^{-\lambda T} > 0 \quad (32)$$

- Thus $m_2(h)$ occurs when λ is as large as possible: $\lambda = \tilde{\lambda} + sh$.
- Thus, from eq.(24):

$$m_2(h) = 1 - e^{-(\tilde{\lambda}+sh)T} - (\tilde{\lambda} + sh)T e^{-(\tilde{\lambda}+sh)T} \quad (33)$$

- The robustness is the greatest h at which:

$$m_2(h) \leq P_c \quad (34)$$

- **Problem:** We can't solve eq.(34) for h .
- **Solution:** No need to.
 - $m_2(h)$ is the inverse of $\hat{h}(P_c)$.
 - Plot of h vs $m_2(h)$ equivalent to plot of $\hat{h}(P_c)$ vs P_c .

4 *Conclusion*

In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§

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In Conclusion

§ **Info-gap uncertainty:**

innovation, discovery, ignorance, surprise.

§ **Info-gap uncertainty is unbounded.**

§ **Optimism:** our models get better all the time.

§ **Realism:** our models are wrong now

(and we don't know where or how much).

§

In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§ Info-gap uncertainty is unbounded.

§ Optimism: our models get better all the time.

§ Realism: our models are wrong now

(and we don't know where or how much).

§ Responsible decision making:

- Specify your goals.
- Maximize your robustness to uncertainty.
- Study the trade offs.
- Exploit windfall opportunities.